Hydrodynamic stability at high Reynolds number and Transition threshold problem

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Reynolds experiment in 1883



Figure: Reynolds experiment

The state of the flow is determined by a dimensionless constant called **Reynolds number**:

$$Re = \rho LU/\mu$$

where ρ density, *L* diameter, *U* velocity, μ viscosity.



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Z. Zhang Peking University Hydrodynamic stability and transition threshold problem

Mathematical model

Navier-Stokes equations:

$$(NS) \quad \begin{cases} \partial_t v - v \Delta v + v \cdot \nabla v + \nabla P = 0 & \text{in} \quad \mathbb{R}_+ \times \Omega, \\ \nabla \cdot v = 0 & \text{in} \quad \mathbb{R}_+ \times \Omega, \\ v = 0 & \text{on} \quad \partial \Omega, \end{cases}$$

where v is the velocity, P is the pressure, and $v = Re^{-1}$ is the viscosity coefficient.

Fluid domain Ω :

Channel domain:

$$\Omega = \{(x, y, z) : x \in \mathbb{T} \text{ or } \mathbb{R}, z \in \mathbb{T}, y \in (-1, 1)\}.$$

• Pipe domain:

$$\Omega = \{x = (x, y, z) : r = \sqrt{x^2 + y^2} < 1, z \in \mathbb{T} \text{ or } z \in \mathbb{R}\}.$$

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Examples of laminar flow





• Plane Poiseuille flow: $(1 - y^2, 0, 0)$



• Pipe Poiseuille flow: $(0, 0, 1 - r^2)$

Our task is to study the stability and instability of laminar flows at high Reynolds number.

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Eigenvalue analysis

Consider the linearized NS system around the laminar flow:

$$\partial_t u - \mathcal{L}_v u = 0.$$

Seek the solution $e^{\lambda t}U$, where U solves the eigenvalue problem:

$$\mathcal{L}_{\nu}U=\lambda U.$$

The system is stable if $\text{Re}\lambda < 0$ and unstable if $\text{Re}\lambda > 0$.

- Plane Couette flow: stable for any Reynolds number(*Romanov*, *Funk. Anal. 1973*).
- Plane Poiseuille flow: stable for Reynolds number less than 5772(*Orszag*, *JFM* 1971).
- Pipe Poiseuille flow: stable at high Reynolds number(*Chen-Wei-Zhang, CPAM online*).

Conjecture: Pipe Poiseuille flow is stable for any Reynolds number.

Experiment and numerical simulation indicated that these flows could transit to turbulence when Reynolds number exceeds a certain critical number. For example,

- Plane Couette flow: transition at Re = 350.
- Plane Poiseuille flow: transition at Re = 1000.

This transition number is much smaller than the critical number predicted by eigenvalue analysis. This kind of transition is called **subcritical transition**(Sommerfeld paradox). Understanding this transition mechanism is of great interest in fluid mechanics.

To shed some light on the transition mechanism, Trefethen et al(*Science 1993*) proposed **Transition threshold problem**:

How much disturbance will lead to the instability of the flow and the dependence of disturbance on Reynolds number?

Mathematical formulation (Bedrossian-Germain-Masmoudi, BAMS 2019):

Given a norm $\|\cdot\|_X$, find a $\beta = \beta(X)$ such that

 $\begin{aligned} \|u_0\|_X \ll Re^{-\beta} \Longrightarrow Stability, \\ \|u_0\|_X \gg Re^{-\beta} \Longrightarrow Instability. \end{aligned}$

The exponent β is referred to as the **transition threshold**.

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The following table shows numerical result (*Lundbladh et al, Transition, Turbulence and Combustion 1994*) and asymptotic analysis result (*Chapman, JFM 2002*) for Couette flow and Poiseuille flow:

Laminar flow	Perturbation	Numerical analysis	Asymptotic analysis
Couette flow	streamwise perturbation	$\beta = 1$	$\beta = 1$
	oblique perturbation	$\beta = \frac{5}{4}$	eta=1
Poiseuille flow	streamwise perturbation	$\beta = \frac{7}{4}$	$\beta = \frac{3}{2}$
	oblique perturbation	$\beta = \frac{7}{4}$	$\beta = \frac{5}{4}$

Mathematical analysis results

3-D Couette flow in $\Omega = \mathbb{T} \times \mathbb{R} \times \mathbb{T}$:

- If X is Gevrey class, then $\beta \leq 1$ (Bedrossian-Germain-Masmoudi, Mem AMS 2021).
- If $X = H^N$, then $\beta \leq \frac{3}{2}$ (Bedrossian-Germain-Masmoudi, Ann Math 2017).
- If $X = H^2$, then $\beta \leq 1$ (Wei-Zhang, CPAM 2021).
- 3-D Couette flow in $\Omega = \mathbb{T} \times [-1, 1] \times \mathbb{T}$:
 - If $X = H^2$, then $\beta \le 1$ (Chen-Wei-Zhang, Mem AMS in press).
- **3-D** Kolmogorov flow in $\Omega = \mathbb{T}_{2\pi\delta} \times \mathbb{T} \times \mathbb{T}, \delta < 1$:
 - If $X = H^2$, then $\beta \leq \frac{7}{4}$ (Li-Wei-Zhang, CPAM 2020).

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The following factors play a crucial role in determining the transition threshold:

- 3-D lift-up: instability mechanism.
- **Boundary layer**: wall modes and also central modes for the Poiseuille flow.
- Inviscid damping: vorticity mixing
- Enhanced dissipation: vorticity mixing
- Null structure of nonlinear terms

The main difficulty of this problem is to reveal how these bad effects and good effects influence nonlinear stability via complex nonlinear interactions.

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Linear inviscid damping

Consider the linearized 2-D Euler equation around shear flow (U(y), 0) in a finite channel:

$$\partial_t \omega + \mathcal{L} \omega = \mathbf{0},$$

where $\omega = \partial_x v^2 - \partial_y v^1$ is the vorticity and

$$\mathcal{L} = U(y)\partial_x + U''(y)\partial_x(-\Delta)^{-1}.$$

In particular, for the Couette flow, we have

$$\partial_t \omega + y \partial_x \omega = 0.$$

In 1907, Orr found that the velocity could decay to zero as $t \rightarrow \infty$. This phenomenon is so called **inviscid damping**, which is similar to **Landau damping** in plasma physics.

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Linear inviscid damping: monotone flow

Theorem. (Wei-Zhang-Zhao, CPAM 2018)

Let $U(y) \in C^4([0,1])$ be a monotone function. Assume that the linearized operator \mathcal{L} has no embedding eigenvalues. If $\int_{\mathbb{T}} \omega_0(x, y) dx = 0$ and $P_d \omega_0 = 0$, where P_d is the spectral projection to $\sigma_d(\mathcal{L})$, then it holds that

1. if $\omega_0(x, y) \in H_x^{-1} H_y^1$, then

$$\|v(t)\|_{L^2} \leq C \langle t \rangle^{-1} \|\omega_0\|_{H^{-1}_x H^1_y};$$

2. if $\omega_0(x, y) \in H_x^{-1}H_y^2$, then

$$\|v^{2}(t)\|_{L^{2}} \leq C \langle t \rangle^{-2} \|\omega_{0}\|_{H^{-1}_{x}H^{2}_{v}}.$$

Remark. The spectral assumption holds automatically when the flow has no inflection points.

Linear inviscid damping: symmetric flow

Consider a class of symmetric flow(Poiseuille flow y^2):

U(y) = U(-y), U'(y) > 0 for y > 0, U'(0) = 0 and U''(0) > 0.

Theorem.(Wei-Zhang-Zhao, Ann PDE 2019)

Assume that \mathcal{L} has no embedding eigenvalues. If $\int_{\mathbb{T}} \omega_0(x, y) dx = 0$ and $P_d \omega_0 = 0$, then it holds that

$$\|v(t)\|_{L^{2}} \leq C\langle t\rangle^{-1} \|\omega_{0}\|_{H^{-1/2}_{x}H^{1}_{y}},$$
$$\|v^{2}(t)\|_{L^{2}} \leq C\langle t\rangle^{-2} \|\omega_{0}\|_{H^{1/2}_{x}H^{2}_{y}}.$$

Remark. For general non-monotone shear flows, we can prove linear inviscid damping in the sense of $\|\widehat{v}(\cdot, \alpha, \cdot)\|_{L^2_{t,u}} \leq C$ for any $\alpha \neq 0$.

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Linear inviscid damping: Kolmogorov flow

Consider the Kolmogorov flow $U(y) = \sin y$ or $\cos y$ in $\Omega = \{(x, y) : x \in \mathbb{T}_{2\pi\delta}, y \in \mathbb{T}\}$ with $\delta < 1$.

Theorem.(Wei-Zhang-Zhao, Adv Math 2020)

If $\int_{\mathbb{T}} \omega_0(x, y) dx = 0$, then it holds

$$\begin{aligned} \|v(t)\|_{L^{2}} &\leq C\langle t\rangle^{-1} \|\omega_{0}\|_{H^{-1/2}_{x}H^{1}_{y}}, \\ \|v^{2}(t)\|_{L^{2}} &\leq C\langle t\rangle^{-2} \|\omega_{0}\|_{H^{1/2}_{x}H^{2}_{y}}. \end{aligned}$$

Remark. For non-monotone shear flows, except the vorticity mixing, a new dynamical phenomenon called **vorticity depletion**(*Bouchet-Morita, Physics D 2010*) has a crucial effect:

$$\lim_{t\to\infty}\omega(t,x,y_c)=0 \quad \text{when } U'(y_c)=0.$$

See [Wei-Zhang-Zhao, Ann PDE 2019] for rigorous proof.

Linear inviscid damping: methods of the proof

The key ingredient of the proof is to solve the inhomogeneous Rayleigh equation: for $c = c_r \pm i\epsilon$, $c_r \in \text{Ran}U$, $\epsilon > 0$

$$(U-c)(\Phi''-\alpha^2\Phi)-U''\Phi=F, \quad \Phi(-1)=\Phi(1)=0.$$

- **Direct method**(*Wei-Zhang-Zhao, CPAM 2018*): construct linearly independent solutions for homogeneous Rayleigh equation.
- Compactness method(Wei-Zhang-Zhao, Ann PDE 2019):

$$\|\Phi\|_{H^1(-1,1)} \leq C \|F\|_{H^1(-1,1)}.$$

Contradiction-compactness argument and blow-up analysis near critical points of U(y).

• Vector field method(Wei-Zhang-Zhu, CMP 2020):

$$[\partial_t + U\partial_x, X] = 0, \quad X = \frac{1}{U'}\partial_y + t\partial_x.$$

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Nonlinear inviscid damping in Gevrey class 2:

- Couette flow(Bedrossian-Masmoudi, Publ Math IHES 2015)
- Stable monotone shear flow(Ionescu-Jia, arXiv 2020 Acta Math)
- Stable monotone shear flow(Masmoudi-Zhao, arXiv 2020)

Negative results:

- Existence of steady non-shear solution near Couette flow in Sobolev space(*Lin-Zeng*, *ARMA 2011*).
- Nonlinear instability in Gevrey class 2+(Deng-Masmoudi, arXiv 2018 CPAM).

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The linearized 2-D NS equation around Couette flow:

$$\partial_t \omega - \nu \Delta \omega + \mathbf{y} \partial_x \omega = \mathbf{0}, \quad \omega(\mathbf{0}) = \omega_\mathbf{0}.$$

If $x \in \mathbb{T}$ and $y \in \mathbb{R}$, then we have

$$\widehat{\omega}(t,k,\eta) = e^{-\nu \int_0^t (k^2 + (\eta - k\tau)^2) d\tau} \widehat{\omega}_0(k,\eta).$$

Due to $\int_0^t (k^2 + (\eta - k\tau)^2) d\tau \ge ck^2 t^3$, if $\int_{\mathbb{T}} \omega_0(x,y) dx = 0$, then
 $\|\omega(t)\|_{L^2} \le C e^{-c\nu^{\frac{1}{3}}t} \|\omega_0\|_{L^2}.$

This decay rate $v^{\frac{1}{3}}$ is much bigger than the diffusion rate v. This phenomenon is so called **enhanced dissipation**.

The linearized 2-D NS equation around Kolmogorov flow:

$$\partial_t \omega + \mathcal{L}_{\nu}(t)\omega = 0, \quad \omega(0) = \omega_0,$$

where

$$\mathcal{L}_{\nu}(t) = -\nu\Delta + \cos y \partial_x (1 + \Delta^{-1}).$$

Beck and Wayne's conjecture(*Proc Roy Soc Edinburgh Sect A 2013*): If $\int_{\mathbb{T}_{2\pi\delta}} \omega_0(x, y) dx = 0$ and $\delta < 1$, then it holds that

$$\|\omega(t)\|_{L^2} \leq C e^{-cv^{\frac{1}{2}t}} \|\omega_0\|_{L^2}.$$

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Linear enhanced dissipation

Three approaches solving Beck and Wayne's conjecture:

1. Wave operator method(*Wei-Zhao-Zhang*, *Adv Math 2020*): construct a wave operator *D* so that

$$D\cos y(1+(\partial_y^2-\alpha^2)^{-1})\omega=\cos yD\omega.$$

2. Resolvent estimate method (Li-Wei-Zhang, CPAM 2020):

$$\|(L_{\nu}-i\lambda)w\|_{L^{2}} \geq C\nu^{\frac{1}{2}}|\beta|^{\frac{1}{2}}(1-\beta^{-2})\|w\|_{L^{2}},$$

where $|\beta| > 1$ and

$$L_{\nu}\mathbf{w} = -\nu\partial_{y}^{2}\mathbf{w} + i\beta\cos y(\mathbf{w} + \varphi), \quad (\partial_{y}^{2} - \beta^{2})\varphi = \mathbf{w}.$$

Enhanced dissipation estimate by Gearhart-Prüss type lemma for m-accretive operator(*wei*, *SCM 2020*).

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Linear enhanced dissipation

3. Hypocoercivity method(Wei-Zhang, SCM 2019):

$$\partial_t \omega + \nu (-\partial_y^2 + \beta^2) \omega - i\beta B \omega = 0, \quad B = \cos y \Big(1 + (\partial_y^2 - \beta^2)^{-1} \Big).$$

The key idea is to introduce the energy functional

$$\Phi(t) = E_0(t) + \alpha_0 v t E_1(t) + \beta_0 v t^2 \mathcal{E}_1(t) + \gamma_0 v t^3 \mathcal{E}_2(t),$$

where $\alpha_0, \beta_0, \gamma_0$ are suitable positive constants and

$$\begin{split} & \mathcal{E}_{0}(t) = \|\omega(t)\|_{*}^{2}, \quad \mathcal{E}_{1}(t) = \|\partial_{y}\omega(t)\|_{*}^{2}, \quad \mathcal{E}_{2}(t) = \|\omega(t)\|_{*}^{2} - \|B\omega(t)\|_{*}^{2}, \\ & \mathcal{E}_{1}(t) = \operatorname{Re}\langle\partial_{y}\omega(t), iC\omega(t)\rangle_{*}, \quad C = -[\partial_{y}, B], \end{split}$$

with new inner product $\langle u, w \rangle_* = \langle u, w - (\beta^2 - \partial_y^2)^{-1} w \rangle$.

Remark. An independent proof (Ibrahim-Maekawa-Masmoudi, Ann PDE 2019); Compactness and resolvent method for general monotone flows(Chen-Wei-Zhang, preprint).

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Chapman toy model

Consider a toy model introduced by Chapman(JFM 2002):

$$\begin{cases} \frac{d\psi_1}{dt} + \epsilon\psi_1 = \phi_2^2, \\ \frac{d\phi_1}{dt} + \epsilon\phi_1 - \psi_1 = 0, \\ \frac{d\psi_2}{dt} + \delta\psi_2 = \phi_1\phi_2, \\ \frac{d\phi_2}{dt} + \delta\phi_2 - \psi_2 = 0. \end{cases}$$

- In physics, ψ₁: streamwise vorticity, φ₁: streamwise streak, (ψ₂, φ₂): oblique modes.
- Enhanced dissipation: $0 < \epsilon \ll \delta \ll 1$ (Couette flow $\delta = \epsilon^{\frac{1}{3}}$).
- ϕ_1 undergoes a transient growth due to lift-up term ψ_1 :

$$|\phi_1(t)| \leq t e^{-\epsilon t} \leq \epsilon^{-1}$$
 for $t \leq \epsilon^{-1}$.

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Chapman toy model: scaling analysis

We introduce the following scaling:

$$t = \epsilon^{-1} \hat{t}, \quad \phi_1 = \delta^2 \hat{\phi}_1, \quad \psi_1 = \epsilon \delta^2 \hat{\psi}_1, \quad \phi_2 = \epsilon \delta \hat{\phi}_2, \quad \psi_2 = \epsilon \delta^2 \hat{\psi}_2.$$

The rescaled toy system takes as follows

$$\begin{cases} \frac{d\hat{\psi}_1}{d\hat{t}} + \hat{\psi}_1 = \hat{\phi}_2^2, \\ \frac{d\hat{\phi}_1}{d\hat{t}} + \hat{\phi}_1 - \hat{\psi}_1 = 0, \\ \frac{\epsilon}{\delta} \frac{d\hat{\psi}_2}{d\hat{t}} + \hat{\psi}_2 = \hat{\phi}_1 \hat{\phi}_2, \\ \frac{\epsilon}{\delta} \frac{d\hat{\phi}_2}{d\hat{t}} + \hat{\phi}_2 - \hat{\psi}_2 = 0. \end{cases}$$

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Chapman toy model: secondary instability

We rewrite the system of oblique modes as follows

$$\partial_t \left(\begin{array}{c} \hat{\psi}_2 \\ \hat{\phi}_2 \end{array} \right) = \frac{\delta}{\epsilon} \left(\begin{array}{cc} -1 & \hat{\phi}_1 \\ 1 & -1 \end{array} \right) \left(\begin{array}{c} \hat{\psi}_2 \\ \hat{\phi}_2 \end{array} \right).$$

Secondary instability of oblique modes:

- if $\hat{\phi}_1 > 1$, the system has an unstable eigenvalue.
- if $\hat{\phi}_1 < 1$, the system is stable and the oblique modes will rapidly decay to zero due to $\frac{\delta}{\epsilon} \gg 1$.

This scaling analysis indicates that the transition amplitude of this toy model is $\epsilon \delta^2$.

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Chapman toy model: transition route

Transition route: Streamwise vorticity \rightarrow Streamwise streak \rightarrow Secondary instability of oblique modes.



Perturbation NS system

We introduce the perturbation around Couette flow (y, 0, 0):

$$v = (y, 0, 0) + u, \quad \nabla \times v = (0, 0, -1) + \omega.$$

Consider the coupled system of $(\Delta u^2, \omega^2)$:

$$\begin{cases} \partial_t (\Delta u^2) - \nu \Delta^2 u^2 + y \partial_x \Delta u^2 = F_1, \\ \partial_t \omega^2 - \nu \Delta \omega^2 + y \partial_x \omega^2 + \partial_z u^2 = F_2, \\ u^2(t, x, \pm 1, z) = \partial_y u^2(t, x, \pm 1, z) = \omega^2(x, \pm 1, z) = 0, \end{cases}$$

where

$$\begin{split} F_{1} &= -(\partial_{x}^{2} + \partial_{z}^{2})(u \cdot \nabla u^{2}) + \partial_{y} \Big[\partial_{x}(u \cdot \nabla u^{1}) + \partial_{z}(u \cdot \nabla u^{3}) \Big], \\ F_{2} &= -\partial_{z}(u \cdot \nabla u^{1}) + \partial_{x}(u \cdot \nabla u^{3}). \end{split}$$

Perturbation NS system

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Let
$$k^2 = \alpha^2 + \beta^2$$
. Then $(u^2_{\alpha\beta}, \omega^2_{\alpha\beta})$ satisfies

$$\begin{cases} \left(\partial_t + i\alpha y + \nu(-\partial_y^2 + k^2)\right)(-\partial_y^2 + k^2)u^2_{\alpha\beta} = F_1^{\alpha,\beta}, \\ \left(\partial_t + i\alpha y + \nu(-\partial_y^2 + k^2)\right)\omega^2_{\alpha\beta} + i\beta u^2_{\alpha\beta} = F_2^{\alpha,\beta}. \end{cases}$$

When $k \neq 0$, nonlinear terms $F_1^{\alpha\beta}$ and $F_2^{\alpha\beta}$ behave as

$$\begin{split} F_{1}^{\alpha\beta} \sim & \left\{ (u^{2}u_{yyy}^{2} + u_{y}^{2}u_{yy}^{2}) + (\omega^{2}u_{yy}^{2} + u^{2}\omega_{yy}^{2} + u_{y}^{2}\omega_{y}^{2}) \\ & + (u^{2}u_{y}^{2} + \omega^{2}\omega_{y}^{2} + u^{2}\omega^{2}) \right\}_{\alpha\beta'} \\ F_{2}^{\alpha\beta} \sim & \left(\omega^{2}\omega^{2} + u^{2}u_{yy}^{2} + u^{2}\omega_{y}^{2} + u_{y}^{2}\omega^{2} \right)_{\alpha\beta}. \end{split}$$

For $F_1^{\alpha\beta}$, the middle part is the worst nonlinear interaction.

Secondary instability of wall mode

Consider the linearized NS system

$$\begin{cases} \left(\partial_t + i\alpha y + \nu(-\partial_y^2 + k^2)\right)(-\partial_y^2 + k^2)u_{\alpha\beta}^2 = 0, \\ \left(\partial_t + i\alpha y + \nu(-\partial_y^2 + k^2)\right)\omega_{\alpha\beta}^2 + i\beta u_{\alpha\beta}^2 = 0. \end{cases}$$

Seek the solution $u_{\alpha\beta}^2 = e^{-i\alpha\lambda t}v$, $\omega_{\alpha\beta}^2 = e^{-i\alpha\lambda t}\eta$. Then (v, η) solves the following eigenvalue system $(R = v^{-1})$:

$$\left\{egin{aligned} &i(\lambda-y)(\partial_y^2-k^2)v+rac{1}{Rlpha}(\partial_y^2-k^2)^2v=0,\ &-i(\lambda-y)\eta-rac{1}{Rlpha}(\partial_y^2-k^2)\eta+rac{ieta}{lpha}v=0. \end{aligned}
ight.$$

Question: how large the perturbation induced by nonlinear interactions could excite unstable eigenvalues?

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Secondary instability of wall mode

Following Chapman's asymptotic analysis, we consider a class of eigenvalues with imaginary part of order $(\alpha R)^{-\frac{1}{3}}$. This class is called **wall modes**, whose eigenfunctions are localized in a region of order $(\alpha R)^{-\frac{1}{3}}$ near the boundary.

To excite unstable eigenvalues, we introduce a perturbation F into the eigenvalue equation of v:

$$i(\lambda - y)(\partial_y^2 - k^2)v + \frac{1}{R\alpha}(\partial_y^2 - k^2)^2v = F.$$

For wall modes, in the inner layer, we have

$$i(\lambda - y)(\partial_y^2 - k^2)v + \frac{1}{R\alpha}(\partial_y^2 - k^2)^2v$$

$$\sim (\alpha R)^{-\frac{1}{3}}(\alpha R)^{\frac{2}{3}}v + (R\alpha)^{-1}(R\alpha)^{\frac{4}{3}}v \sim (\alpha R)^{\frac{1}{3}}v.$$

The worst nonlinear interaction:

$$F \sim \bar{\eta} v_{yy} \sim \bar{\eta} (\alpha R)^{\frac{2}{3}} v, \quad \bar{\eta} \sim \omega_{0\beta}^{2}.$$

To excite unstable eigenvalues, *F* should have the same scale as the left hand side. So, $\bar{\eta}$ should be of order $(\alpha R)^{-\frac{1}{3}}$ in the inner layer, which requires $\bar{\eta} \sim O(1)$ in the outer layer due to $\partial_y \bar{\eta} \sim \bar{\eta}$ and $\bar{\eta}(-1) = 0$.

On the other hand, due to the lift-up effect, we have

$$R\bar{v} \sim \bar{\eta} = O(1) \Longrightarrow \bar{v} \sim R^{-1}.$$

This scaling analysis suggests that the transition threshold $\beta = 1$ for the Couette flow.

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Transition threshold for 3-D Couette flow

Theorem.(Chen-Wei-Zhang, Mem AMS in press)

There exist constants c, C > 0 independent of v so that if $||u_0||_{H^2} \le c_0 v$, then it holds

1. Uniform bounds of streamwise modes:

$$\begin{split} \|\bar{u}^{1}(t)\|_{H^{2}} + \|\bar{u}^{1}(t)\|_{L^{\infty}} &\leq C\nu^{-1}\min(\nu t + \nu^{2/3}, e^{-\nu t})\|u_{0}\|_{H^{2}}, \\ \|\bar{u}^{2}(t)\|_{H^{2}} + \|\bar{u}^{3}(t)\|_{H^{1}} + \|(\bar{u}^{2}, \bar{u}^{3})(t)\|_{L^{\infty}} &\leq Ce^{-\nu t}\|u_{0}\|_{H^{2}}. \end{split}$$

2. Uniform bounds of oblique modes:

 $\begin{aligned} \|(\partial_{x},\partial_{z})\partial_{x}u_{\neq}(t)\|_{L^{2}} + \nu^{1/6}\|(u_{\neq}^{1},u_{\neq}^{3})(t)\|_{L^{\infty}} &\leq Ce^{-c\nu^{1/3}t}\|u_{0}\|_{H^{2}},\\ \|(\partial_{x},\partial_{z})\nabla_{x,y,z}u_{\neq}^{2}(t)\|_{L^{2}} + \|u_{\neq}^{2}(t)\|_{L^{\infty}} &\leq Ce^{-c\nu^{1/3}t}\|u_{0}\|_{H^{2}}. \end{aligned}$

Here $\bar{u} = \int_{\mathbb{T}} u dx$ and $u_{\neq} = u - \bar{u}$.

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Key ingredients(I): space-time estimates

To control Δu^2 and ω^2 , we need to consider the linearized NS system with Navier-slip boundary condition:

$$\begin{cases} \partial_t \omega - \nu (\partial_y^2 - k^2) \omega + i \alpha y \omega = i \alpha f_1 + \partial_y f_2 + i \beta f_3, \\ \omega|_{y=\pm 1} = 0, \quad \omega|_{t=0} = \omega_{in}, \end{cases}$$
(1)

and with non-slip boundary condition:

$$\begin{cases} \partial_t \omega - \nu (\partial_y^2 - k^2) \omega + i \alpha y \omega = i \alpha f_1 + \partial_y f_2 + i \beta f_3, \\ (\partial_y^2 - k^2) \varphi = \omega, \quad \partial_y \varphi|_{y=\pm 1} = \varphi|_{y=\pm 1} = 0, \\ \omega|_{t=0} = \omega_{in}. \end{cases}$$
(2)

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Key ingredients(I): space-time estimates

For the linearized system (2), we prove that

$$\begin{split} &\|\eta\|\|e^{a\nu^{\frac{1}{3}}t}(\partial_{y},k)\varphi\|_{L^{\infty}L^{2}}+\nu^{\frac{1}{4}}\|e^{a\nu^{\frac{1}{3}}t}\omega\|_{L^{\infty}L^{2}}+|\alpha k|^{\frac{1}{2}}\|e^{a\nu^{\frac{1}{3}}t}(\partial_{y},k)\varphi\|_{L^{2}L^{2}}\\ &+\nu^{\frac{3}{4}}\|e^{a\nu^{\frac{1}{3}}t}\partial_{y}\omega\|_{L^{2}L^{2}}+\nu^{\frac{1}{2}}|k|\|e^{a\nu^{\frac{1}{3}}t}\omega\|_{L^{2}L^{2}}\\ &\leq C\left(|k|^{-1}\|\partial_{y}\omega_{in}\|_{L^{2}}+\|\omega_{in}\|_{L^{2}}\right)+C\nu^{-\frac{1}{2}}\|e^{a\nu^{\frac{1}{3}}t}(f_{1},f_{2},f_{3})\|_{L^{2}L^{2}}. \end{split}$$

Remarks.

- The rapid decay $e^{av^{\frac{1}{3}}t}$ is due to enhanced dissipation.
- $|\alpha k|^{\frac{1}{2}} ||e^{av^{\frac{1}{3}}t} (\partial_y, k)\varphi||_{L^2L^2}$ is due to inviscid damping.
- The loss $v^{\frac{1}{4}}$ in front of $||e^{av^{\frac{1}{3}}t}\omega||_{L^{\infty}L^{2}}$ is due to the boundary layer effect.
- The proof is based on resolvent estimate method developed in [*Chen-Li-Wei-Zhang, ARAM 2020*].

Key ingredients(II): exclude secondary instability

Consider the linearized NS system around the flow (V(y, z), 0, 0), which is a small perturbation of Couette flow, i.e.,

$$\|V-y\|_{H^4} \leq \varepsilon_0, \quad V(y,z)-y|_{y=\pm 1}=0,$$

with ε_0 small enough but independent of ν . We denote

$$\mathbb{A}_{\nu,\nu} u = \mathbb{P}\Big(\nu\Delta u - V\partial_x u - (\partial_y V(u^2 + \kappa u^3), 0, 0)\Big),$$

here \mathbb{P} is the Leray projection and $\kappa = \partial_z V / \partial_y V$. The linearized NS system takes

$$\partial_t u_{\neq} - \mathbb{A}_{\nu, V} u_{\neq} = F.$$

The key point is to exclude the existence of unstable eigenvalues of $\mathbb{A}_{\nu,V}$.

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Key ingredients(II): exclude secondary instability

Motived by [*Wei-Zhang, CPAM 2021*], **the key idea** is to introduce $W = u^2 + \kappa u^3$ and $U = u^3$. The problem is reduced to solving the following OS system:

$$\begin{cases} -\nu\Delta W + i\alpha(V(y,z) - \lambda)W + (\partial_y + \kappa\partial_z)p^{L1} \\ = G_1 - \nu(\Delta\kappa)U - 2\nu\nabla\kappa\cdot\nabla U, \\ -\nu\Delta U + i\alpha(V(y,z) - \lambda)U + \partial_z p^{L1} = G_2, \\ \Delta p^{L1} = -2i\alpha\partial_y VW, \quad W = \partial_y W = U = 0 \quad \text{on } y = \pm 1, \end{cases}$$

where $\lambda \in \mathbb{R}$. It holds that

$$\begin{split} \nu^{\frac{1}{3}} \Big(\|\partial_{x}^{2}U\|_{L^{2}}^{2} + \|\partial_{x}(\partial_{z} - \kappa\partial_{y})U\|_{L^{2}}^{2} \Big) + \nu \Big(\|\nabla\partial_{x}^{2}U\|_{L^{2}}^{2} + \|\nabla\partial_{x}(\partial_{z} - \kappa\partial_{y})U\|_{L^{2}}^{2} \Big) \\ + \nu^{\frac{1}{3}} \|\partial_{x}\nabla W\|_{L^{2}}^{2} + \nu \|\partial_{x}\Delta W\|_{L^{2}}^{2} + \nu^{\frac{5}{3}} \|\partial_{x}\Delta U\|_{L^{2}}^{2} \\ \leq C\nu^{-1} \Big(\|\nabla G_{1}\|_{L^{2}}^{2} + \|\partial_{x}G_{2}\|_{L^{2}}^{2} \Big). \end{split}$$

(1) Energy functional of streamwise modes.

A key decomposition: $\overline{u}^1 = \overline{u}^{1,0} + \overline{u}^{1,\neq}$ with

$$\begin{cases} (\partial_t - \nu \Delta) \bar{u}^{1,0} + \bar{u}^2 + \bar{u}^2 \partial_y \bar{u}^{1,0} + \bar{u}^3 \partial_z \bar{u}^{1,0} = 0, \\ (\partial_t - \nu \Delta) \bar{u}^{1,\neq} + \bar{u}^2 \partial_y \bar{u}^{1,\neq} + \bar{u}^3 \partial_z \bar{u}^{1,\neq} + \overline{u_{\neq}} \cdot \nabla u_{\neq}^1 = 0, \\ \bar{u}^{1,0}|_{y=\pm 1} = \bar{u}^{1,\neq}|_{y=\pm 1} = 0, \\ \bar{u}^{1,0}|_{t=0} = 0, \quad \bar{u}^{1,\neq}|_{t=0} = \bar{u}^1(0). \end{cases}$$

The main reason making this decomposition is to avoid estimating high order derivatives of oblique modes.

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The energy E_1 of \bar{u}^1 is defined by

$$\begin{split} E_{1} = & \|\bar{u}^{1,0}\|_{L^{\infty}H^{4}} + \nu^{-1} \|\partial_{t}\bar{u}^{1,0}\|_{L^{\infty}H^{2}} + \nu^{-\frac{1}{2}} \|\partial_{t}\bar{u}^{1,0}\|_{L^{2}H^{3}} \\ & + \nu^{-2/3} \Big(\|\bar{u}^{1,\neq}\|_{L^{\infty}H^{2}} + \nu^{\frac{1}{2}} \|\nabla\bar{u}^{1,\neq}\|_{L^{2}H^{2}} \Big). \end{split}$$

The energy E_2 of (\bar{u}^2, \bar{u}^3) is defined by

$$\begin{split} E_{2} = & \|\Delta \bar{u}^{2}\|_{L^{\infty}L^{2}} + \nu^{\frac{1}{2}} \|\nabla \Delta \bar{u}^{2}\|_{L^{2}L^{2}} + \nu^{\frac{1}{2}} \|\Delta \bar{u}^{2}\|_{L^{2}L^{2}} + \nu^{-\frac{1}{2}} \|\partial_{t} \nabla \bar{u}^{2}\|_{L^{2}L^{2}} \\ & + \|\nabla \bar{u}^{3}\|_{L^{\infty}L^{2}} + \nu^{\frac{1}{2}} \|\Delta \bar{u}^{3}\|_{L^{2}L^{2}} + \nu^{\frac{1}{2}} \|\nabla \bar{u}^{3}\|_{L^{2}L^{2}} + \nu^{-\frac{1}{2}} \|\partial_{t} \bar{u}^{3}\|_{L^{2}L^{2}} \\ & + \|\min((\nu^{\frac{2}{3}} + \nu t)^{\frac{1}{2}}, 1 - y^{2})\Delta \bar{u}^{3}\|_{L^{\infty}L^{2}} \\ & + \nu^{-\frac{1}{2}} \|\min((\nu^{\frac{2}{3}} + \nu t)^{\frac{1}{2}}, 1 - y^{2})\nabla \partial_{t} \bar{u}^{3}\|_{L^{\infty}L^{2}} \\ & + \nu^{\frac{1}{2}} \|\min((\nu^{\frac{2}{3}} + \nu t)^{\frac{1}{2}}, 1 - y^{2})\nabla \Delta \bar{u}^{3}\|_{L^{2}L^{2}}. \end{split}$$

The estimates of E_1 , E_2 are based on direct energy estimate for the system of streamwise modes.

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(2) Energy functional of oblique modes(semilinear part):

$$E_3 = E_{3,0} + E_{3,1}$$

where

$$\begin{split} E_{3,0} = &\nu^{\frac{1}{2}} \| e^{2\epsilon\nu^{\frac{1}{3}}t} (\partial_{x}, \partial_{z}) \Delta u_{\neq}^{2} \|_{L^{2}L^{2}} + \nu^{\frac{3}{4}} \| e^{2\epsilon\nu^{\frac{1}{3}}t} \nabla \Delta u_{\neq}^{2} \|_{L^{2}L^{2}} \\ &+ \| e^{2\epsilon\nu^{\frac{1}{3}}t} (\partial_{x}, \partial_{z}) \nabla u_{\neq}^{2} \|_{L^{\infty}L^{2}} + \| e^{2\epsilon\nu^{\frac{1}{3}}t} \partial_{x} \nabla u_{\neq}^{2} \|_{L^{2}L^{2}} \\ &+ \| e^{2\epsilon\nu^{\frac{1}{3}}t} (\partial_{x}^{2} + \partial_{z}^{2}) u_{\neq}^{3} \|_{L^{\infty}L^{2}} + \nu^{\frac{1}{2}} \| e^{2\epsilon\nu^{\frac{1}{3}}t} (\partial_{x}^{2} + \partial_{z}^{2}) \nabla u_{\neq}^{3} \|_{L^{2}L^{2}}, \\ E_{3,1} = &\nu^{\frac{1}{3}} \Big(\| e^{2\epsilon\nu^{\frac{1}{3}}t} \nabla \omega_{\neq}^{2} \|_{L^{\infty}L^{2}} + \nu^{\frac{1}{2}} \| e^{2\epsilon\nu^{\frac{1}{3}}t} \Delta \omega_{\neq}^{2} \|_{L^{2}L^{2}} \Big). \end{split}$$

The estimate of E_3 is based on space-time estimates for the linearized NS system (1) and (2).

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(3) Energy functional of oblique modes(quasilinear part):

$$E_4 = v^{1/6} \| e^{3\epsilon v^{1/3}t} \partial_x^2 u_{\neq}^2 \|_{L^2 L^2} + v^{1/6} \| e^{3\epsilon v^{1/3}t} \partial_x^2 u_{\neq}^3 \|_{L^2 L^2}$$

This part is crucial to control nonlinear interactions with lift-up effect such as $\overline{u}^1 \partial_x u^j_{\neq}$ and $u^j_{\neq} \partial_j \overline{u}^1 (j = 2, 3)$:

$$e^{2\epsilon\nu^{1/3}t} \left| \overline{u}^1 \partial_x u_{\neq}^j \right| \lesssim (\nu t) e^{2\epsilon\nu^{1/3}t} \left| \partial_x u_{\neq}^j \right| \lesssim e^{3\epsilon\nu^{1/3}t} \left| \partial_x u_{\neq}^j \right|.$$

The estimate of E_4 is based on space-time estimates for the coupled system of (U, W).

In conclusion:

$$E_1 \sim o(1), \quad E_2 \sim o(\nu), \quad E_3 \sim o(\nu), \quad E_4 \sim o(\nu).$$

Open problems

- Plane Couette flow in $\mathbb{R} \times [-1, 1] \times \mathbb{T}$: **conjecture:** $\beta < 1$.
- Plane Poiseuille flow in $\mathbb{T} \times [-1, 1] \times \mathbb{T}$: **conjecture**: $\beta = \frac{3}{2}$.
- Kolmogorov flow in $\mathbb{T}_{2\pi\delta} \times \mathbb{T} \times \mathbb{T}$, $\delta < 1$: **conjecture:** $\beta = \frac{3}{2}$. Known result $\beta \leq \frac{7}{4}$ (*Li-Wei-Zhang, CPAM 2020*).
- Pipe Poiseuille flow:
 - Experiment result(*Hof-Juel-Mullin*, *PRL 2004*): $\beta = 1$;
 - Numerical result(Mellibovskya-Meseguer, Phys Fluids 2007): $\beta = 1$;
 - Asymptotic analysis result: $\beta = 1$.

Conjecture: $\beta = 1$.

• Other physical system such as Boussinesq system, MHD, Compressible NS etc.

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Thanks a lot for your attention!

Z. Zhang Peking University Hydrodynamic stability and transition threshold problem

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